



ubuntu<sup>o</sup>core

## Ubuntu Core Porting

Board enablement experience sharing

<https://www.ubuntu.com/core>

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# Agenda



- ⬡ Prerequisites
- ⬡ Snappy booting process
- ⬡ Gadget snap creation
- ⬡ Kernel snap creation
- ⬡ Image creation
- ⬡ Issues and Challenges
- ⬡ Q&A

The official guide for porting used  
the github project I contributed ...

<https://github.com/xapp-le/SnappyUbuntuCore>

v.s

<https://docs.ubuntu.com/core/en/guides/build-device/board-enablement>

To build a Ubuntu Core image, three snaps are essential and fundamental

OS snap

Gadget snap

Kernel snap

# Prerequisites



## Using roseapple-pi as example

- ❏ Install snappy tools and cross toolchains

```
$apt-get install -y build-essential u-boot-tools lzop  
debootstrap gcc-arm-linux-gnueabihf device-tree-compiler  
$apt-get install -y snapcraft snap ubuntu-image
```

- ❏ Fetch snappy builder - a script-based tool

```
$git clone https://github.com/xapp-le/SnappyUbuntuCore.git
```

- ❏ Get BSP from vendor
  - Check u-boot version
  - Check kernel version
  - Check image layout

# Case study



For MT7623

## Image layout

start	size	binary	usage
0	2K	<u>bromhdr.bin</u>	Rom used and Available for partition table etc.
2	318KB	preloader_iotg7683p1_emmc.bin	Mediatek preloader
320	512KB	u-boot.bin	u-boot
842	128KB		environment
970	54KB		reserved
1024	END		Free for partitions

# Prerequisites



## Signature key for store upload

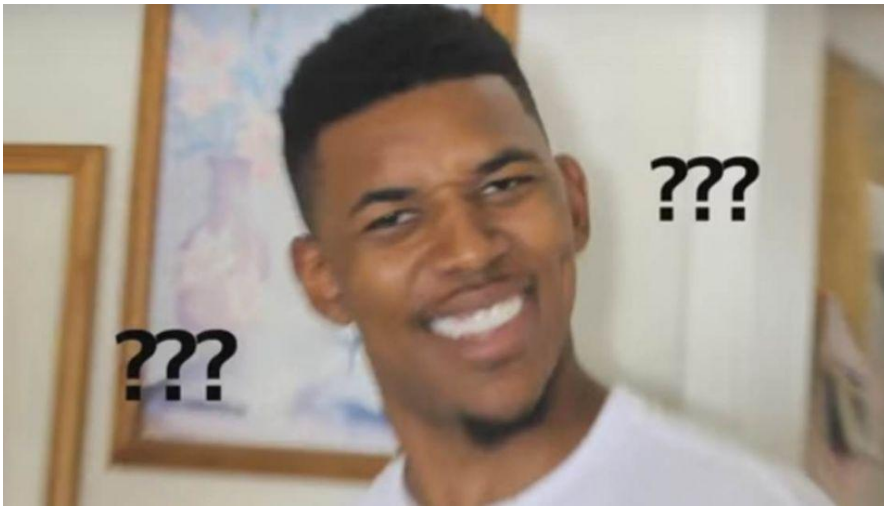
- Create a key

```
$snapcraft login  
$snap create-key <key-name>
```

- Register a key to store

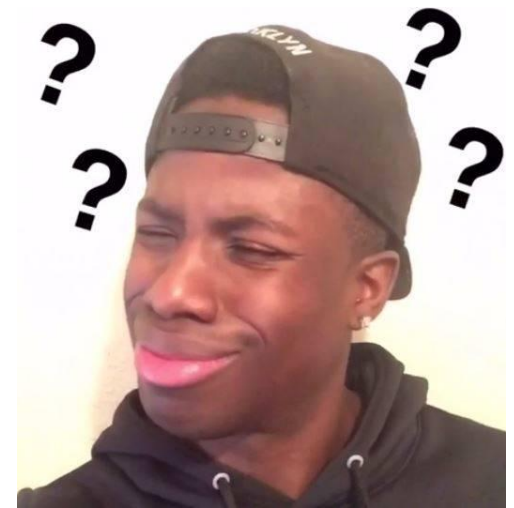
```
$snapcraft register-key
```

- For backup purposes, snap keys are stored under `~/.snap/gnupg`



## Assertions

這三小？





A signed document to make sure our system can be trusted on the device according to snap policy

Assertions have different types - model/serial/account...

# Model assertion



To build an image, it is required you have a signed model assertion

## 🏠 Create a json format

```
{
  "type": "model",
  "authority-id": "<your store account id>",
  "brand-id": "<your store account id>",
  "series": "16",
  "model": "roseapple",
  "architecture": "armhf",
  "gadget": "roseapple-pi",
  "kernel": "roseapple-pi-kernel",
  "timestamp": "<timestamp>"
}
```

# Model assertion



To build an image, it is required you have a signed model assertion

## Sign it

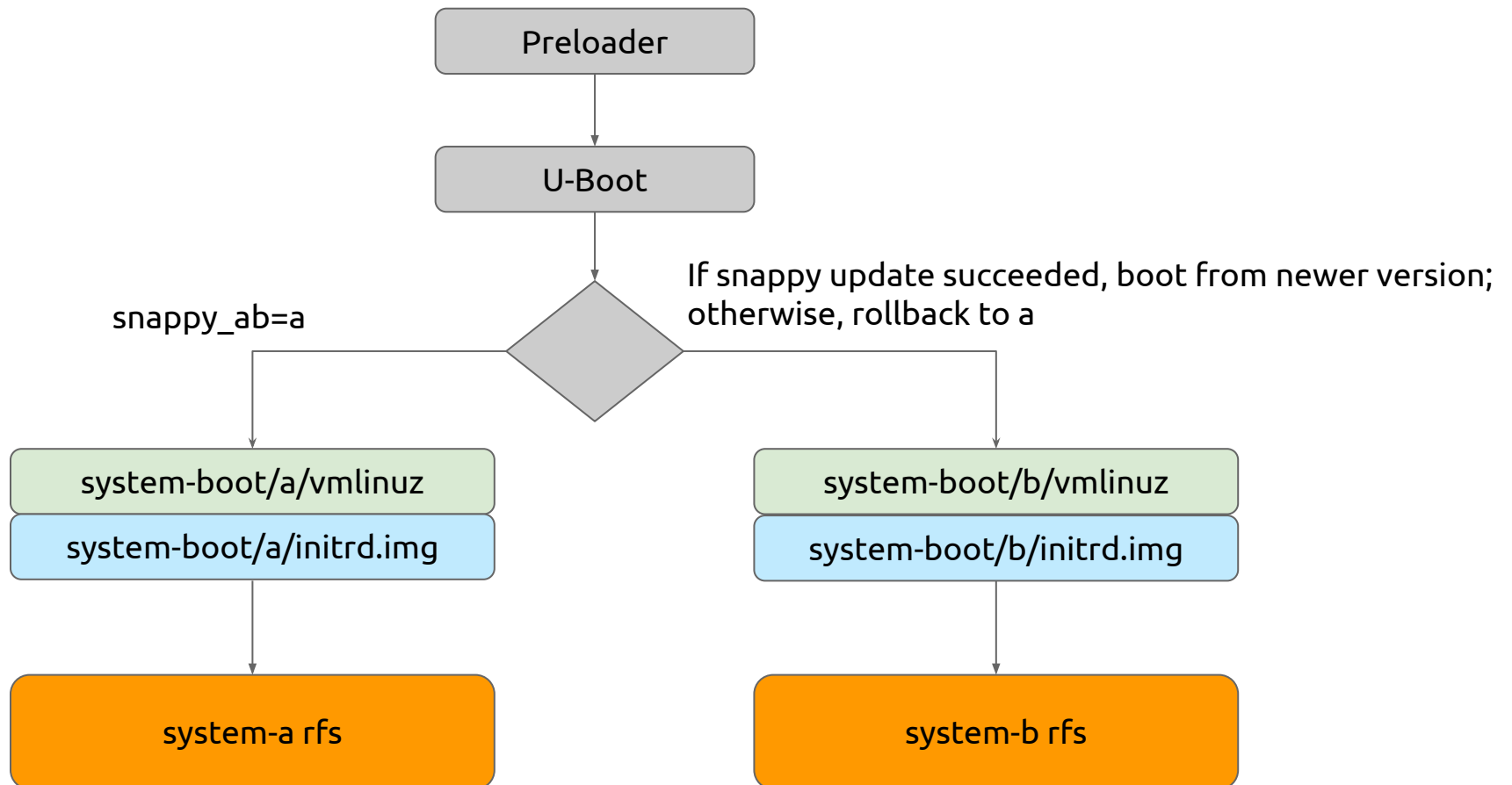
```
$cat roseapple-model.json | snap sign -k <key-name> &>  
roseapple.model
```

# Snappy Booting Process

# Snappy booting logic



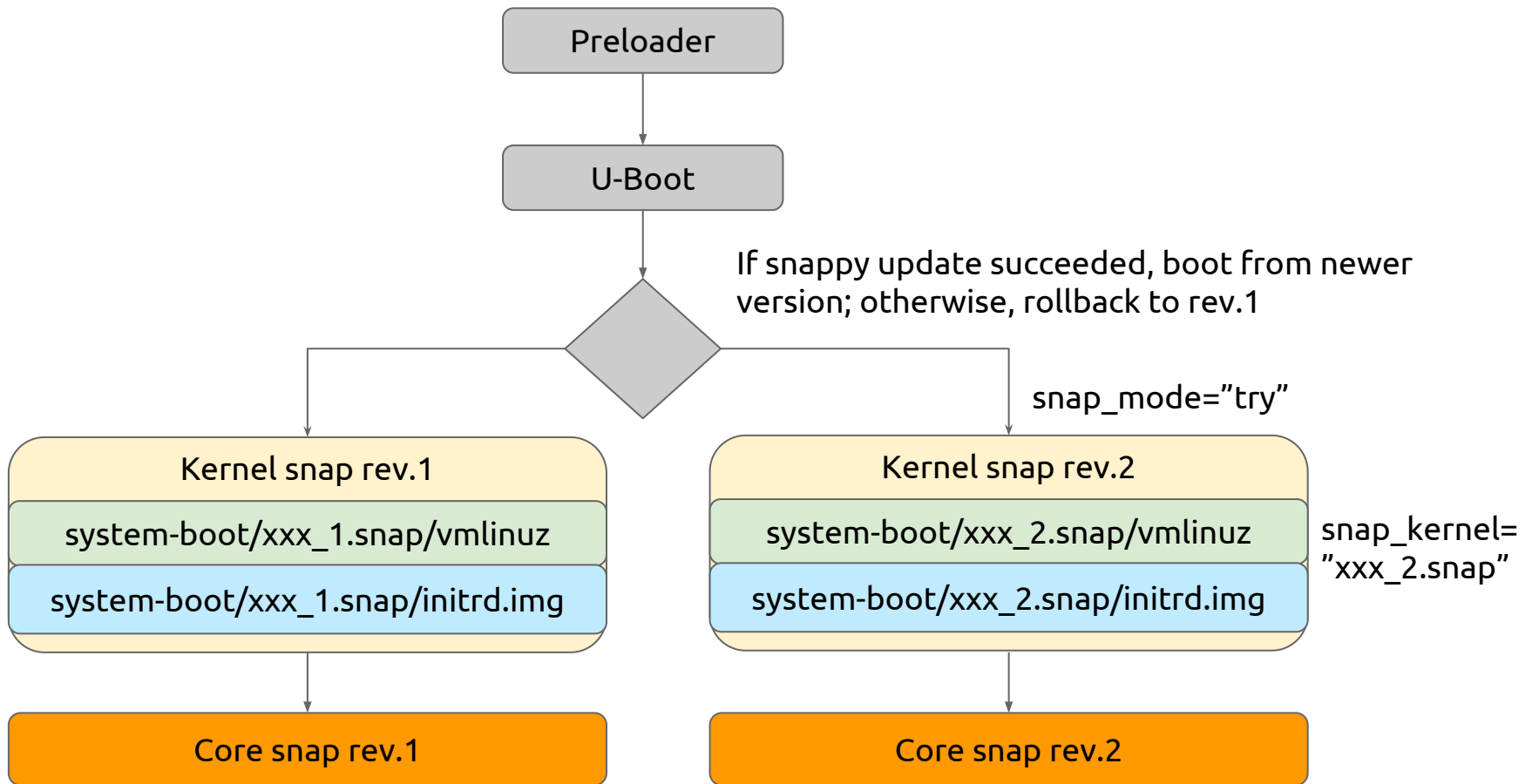
Recall 15.04 system-AB



# Snappy booting logic



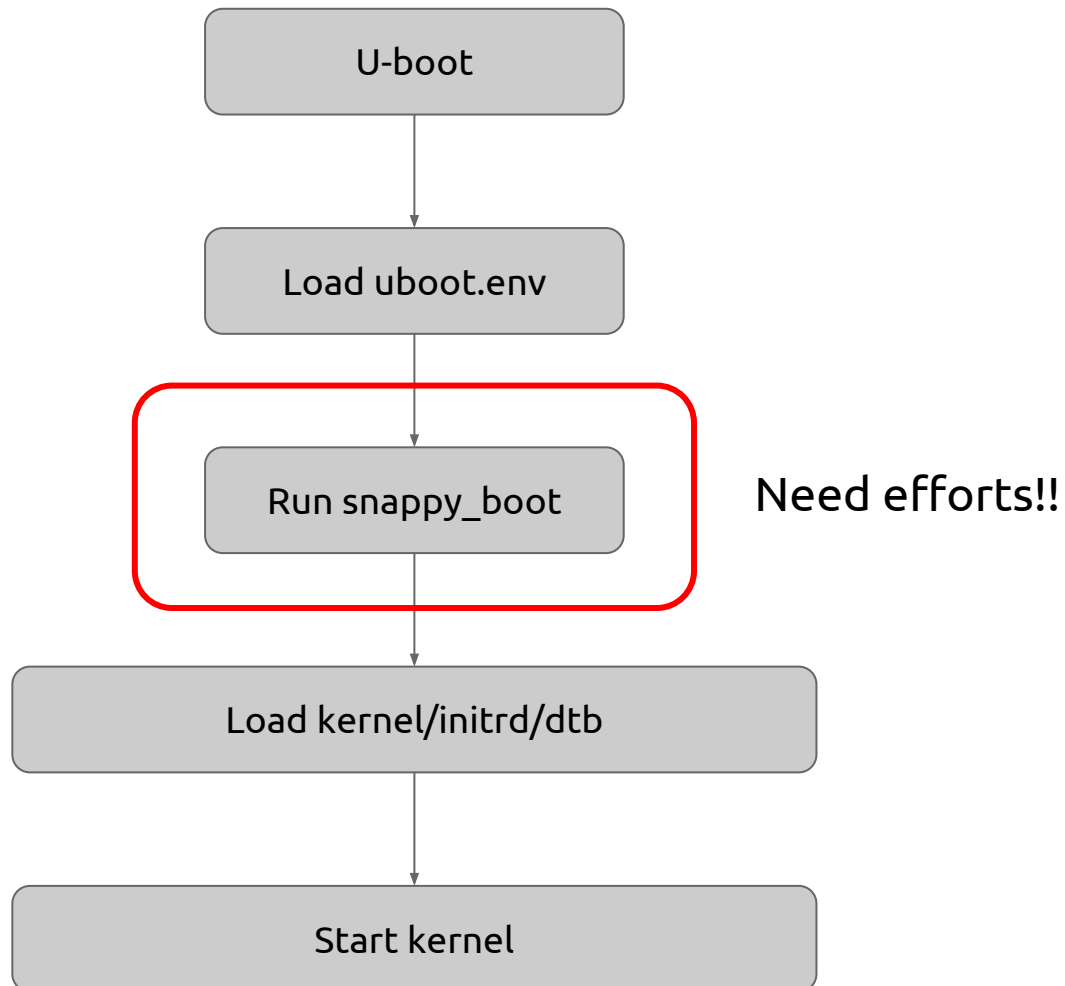
Ubuntu Core 16



# Snappy booting logic: U-boot part



All the things U-boot needs to do



# Gadget snap creation



# Create a gadget snap



## Pack boot parts together as snap

- ◉ Simplest way
  - Define a snapcraft.yaml
  - Define a gadget.yaml
  - Define a uboot.env.in

- ◉ Then use snapcraft cmd

```
$snapcraft --target-arch=armhf -d
```

[1] <https://ograblog.wordpress.com/2017/05/30/building-u-boot-gadget-snap-packages-from-source/>

[2] <https://ograblog.wordpress.com/2017/06/13/patching-u-boot-for-use-in-an-ubuntu-core-gadget-snap/>

[3] <https://github.com/ogra1/sabrelite-gadget>

# Kernel snap creation

# Create a kernel snap



To fit all the features that snapd required

- ⬢ Backport the snappy specific patches [2]
- ⬢ Backport the latest apparmor asap [3]
- ⬢ Use snapcraft.yaml to set all the configs the board needs
  - Also can apply additional patches and firmwares
  
- ⬢ Then use snapcraft cmd

```
$snapcraft --target-arch=armhf -d
```

[1] <https://github.com/xapp-le/kernel/tree/Ubuntu-Snappy-Core>

[2] <https://github.com/snapcore/sample-kernels>

[3] <http://kernel.ubuntu.com/git/jj/linux-apparmor-backports/refs/heads>

# Image creation

# Build an image



## Use ubuntu-image tool

- ❏ “--extra-snaps” can fetch a snap from store or local path
- ❏ Instruction

```
$sudo ubuntu-image \  
-c [edge|beta|candidate|stable] \  
--image-size 4G \  
--extra-snaps <gadget snap> \  
--extra-snaps <kernel snap> \  
--extra-snaps <preinstalled snaps> <model assertion file>
```

```
$sudo ubuntu-image \  
-c stable \  
--image-size 4G \  
--extra-snaps roseapple-pi_16.04-1.5_armhf.snap \  
--extra-snaps roseapple-pi-kernel_3.10.37_armhf.snap \  
--extra-snaps snapweb roseapple.model
```

# Issues and challenges



## Some tips

- ◉ 3.1x Kernel porting
  - Snapd needs some features introduced from new apparmor
  - It may need to backport from jj
    - v3.10.y-aa3.5-beta1
- ◉ Device nodes are managed by snapd and used through **snap interface**
  - Gadget snap can define slots of interface for any hardware
- ◉ Debugging
  - Boot partition
  - Kernel cmdline
  - syslog

[1] <http://snapcraft.io/>

[2] <https://dashboard.snapcraft.io/>

# Issues and challenges



If you're interested in any project on snapcore[1]

- ◻ snapd
  - <https://github.com/snapcore/snapd>
- ◻ snapcraft
  - <https://github.com/snapcore/snapcraft>
- ◻ snapweb
  - <https://github.com/snapcore/snapweb>

[1] <https://github.com/snapcore>



Q & A

Try to use Core as playground